

Robust A Posteriori Error Estimates for Non-Stationary Convection-Diffusion Problems

R. Verfürth

Fakultät für Mathematik
Ruhr-Universität Bochum

www.ruhr-uni-bochum.de/num1

Paris / July 7th, 2010

Goal

Goal

Establish residual a posteriori error estimates for SUPG-discretizations of non-stationary convection-diffusion problems which yield upper and lower bounds for the energy norm of the error that are uniform with respect to all possible relative sizes of convection to diffusion.

Outline

Variational Problem

Outline

Variational Problem

Discretization

Outline

Variational Problem

Discretization

A Posteriori Error Analysis



Differential Equation



Differential Equation

$$\begin{aligned}\partial_t u - \operatorname{div}(d\nabla u) + \mathbf{a} \cdot \nabla u + ru &= f && \text{in } \Omega \times (0, T] \\ u &= 0 && \text{on } \Gamma \times (0, T] \\ u &= u_0 && \text{in } \Omega\end{aligned}$$



Differential Equation

$$\begin{aligned}\partial_t u - \operatorname{div}(d \nabla u) + \mathbf{a} \cdot \nabla u + ru &= f && \text{in } \Omega \times (0, T] \\ u &= 0 && \text{on } \Gamma \times (0, T] \\ u &= u_0 && \text{in } \Omega\end{aligned}$$

- ▶ $d > 0$



Differential Equation

$$\begin{aligned}\partial_t u - \operatorname{div}(d\nabla u) + \mathbf{a} \cdot \nabla u + ru &= f && \text{in } \Omega \times (0, T] \\ u &= 0 && \text{on } \Gamma \times (0, T] \\ u &= u_0 && \text{in } \Omega\end{aligned}$$

- ▶ $d > 0$
- ▶ $r \geq 0$

Differential Equation

$$\begin{aligned}\partial_t u - \operatorname{div}(d\nabla u) + \mathbf{a} \cdot \nabla u + ru &= f && \text{in } \Omega \times (0, T] \\ u &= 0 && \text{on } \Gamma \times (0, T] \\ u &= u_0 && \text{in } \Omega\end{aligned}$$

- ▶ $d > 0$
- ▶ $r \geq 0$
- ▶ $\mathbf{a} \in C^1(\Omega \times (0, T])^d$



Differential Equation

$$\begin{aligned}\partial_t u - \operatorname{div}(d \nabla u) + \mathbf{a} \cdot \nabla u + r u &= f && \text{in } \Omega \times (0, T] \\ u &= 0 && \text{on } \Gamma \times (0, T] \\ u &= u_0 && \text{in } \Omega\end{aligned}$$

- ▶ $d > 0$
- ▶ $r \geq 0$
- ▶ $\mathbf{a} \in C^1(\Omega \times (0, T])^d$
- ▶ $\operatorname{div} \mathbf{a} = 0$ in $\Omega \times (0, T]$



Norms



Norms

- ▶ Energy norm

$$\|v\| = \{d\|\nabla v\|^2 + r\|v\|^2\}^{\frac{1}{2}}$$



Norms

- ▶ Energy norm

$$\|v\| = \{d\|\nabla v\|^2 + r\|v\|^2\}^{\frac{1}{2}}$$

- ▶ Dual norm

$$\|\varphi\|_* = \sup_{v \in H_0^1(\Omega) \setminus \{0\}} \frac{\langle \varphi, v \rangle}{\|v\|}$$

Norms

- ▶ Energy norm

$$\|v\| = \{d\|\nabla v\|^2 + r\|v\|^2\}^{\frac{1}{2}}$$

- ▶ Dual norm

$$\|\varphi\|_* = \sup_{v \in H_0^1(\Omega) \setminus \{0\}} \frac{\langle \varphi, v \rangle}{\|v\|}$$

- ▶ Error norm

$$\|u\|_{X(a,b)} = \left\{ \text{ess. sup}_{t \in (a,b)} \|u(\cdot, t)\|^2 + \int_a^b \|u(\cdot, t)\|^2 dt + \int_a^b \|(\partial_t u + \mathbf{a} \cdot \nabla u)(\cdot, t)\|_*^2 dt \right\}^{\frac{1}{2}}$$

Meshes and Spaces



Meshes and Spaces

- ▶ $\mathcal{I} = \{(t_{n-1}, t_n] : 1 \leq n \leq N_{\mathcal{I}}\}$ partition of $[0, T]$.

Meshes and Spaces

- ▶ $\mathcal{I} = \{(t_{n-1}, t_n] : 1 \leq n \leq N_{\mathcal{I}}\}$ partition of $[0, T]$.
- ▶ $\tau_n = t_n - t_{n-1}$.

Meshes and Spaces

- ▶ $\mathcal{I} = \{(t_{n-1}, t_n] : 1 \leq n \leq N_{\mathcal{I}}\}$ partition of $[0, T]$.
- ▶ $\tau_n = t_n - t_{n-1}$.
- ▶ \mathcal{T}_n , $0 \leq n \leq N_{\mathcal{I}}$, affine equivalent, admissible, shape regular partitions of Ω .



Meshes and Spaces

- ▶ $\mathcal{I} = \{(t_{n-1}, t_n] : 1 \leq n \leq N_{\mathcal{I}}\}$ partition of $[0, T]$.
- ▶ $\tau_n = t_n - t_{n-1}$.
- ▶ \mathcal{T}_n , $0 \leq n \leq N_{\mathcal{I}}$, affine equivalent, admissible, shape regular partitions of Ω .
- ▶ **Transition condition:** There is a common refinement $\tilde{\mathcal{T}}_n$ of \mathcal{T}_n and \mathcal{T}_{n-1} such that $h_K \leq ch_{K'}$ for all $K \in \mathcal{T}_n$ and all $K' \in \tilde{\mathcal{T}}_n$ with $K' \subset K$.



Meshes and Spaces

- ▶ $\mathcal{I} = \{(t_{n-1}, t_n] : 1 \leq n \leq N_{\mathcal{I}}\}$ partition of $[0, T]$.
- ▶ $\tau_n = t_n - t_{n-1}$.
- ▶ \mathcal{T}_n , $0 \leq n \leq N_{\mathcal{I}}$, affine equivalent, admissible, shape regular partitions of Ω .
- ▶ **Transition condition:** There is a common refinement $\tilde{\mathcal{T}}_n$ of \mathcal{T}_n and \mathcal{T}_{n-1} such that $h_K \leq ch_{K'}$ for all $K \in \mathcal{T}_n$ and all $K' \in \tilde{\mathcal{T}}_n$ with $K' \subset K$.
- ▶ $V_n \subset H_0^1(\Omega)$ finite element space corresponding to \mathcal{T}_n .



Discrete Problem



Discrete Problem

Find $u_{\mathcal{T}_n}^n \in X_n$, $0 \leq n \leq N_{\mathcal{I}}$, such that

Discrete Problem

Find $u_{\mathcal{T}_n}^n \in X_n$, $0 \leq n \leq N_{\mathcal{I}}$, such that $u_{\mathcal{T}_0}^0 = \pi_0 u_0$

Discrete Problem

Find $u_{\mathcal{T}_n}^n \in X_n$, $0 \leq n \leq N_{\mathcal{I}}$, such that $u_{\mathcal{T}_0}^0 = \pi_0 u_0$
and, for $n = 1, \dots, N_{\mathcal{I}}$ and all $v_{\mathcal{T}_n} \in X_n$

Discrete Problem

Find $u_{\mathcal{T}_n}^n \in X_n$, $0 \leq n \leq N_{\mathcal{I}}$, such that $u_{\mathcal{T}_0}^0 = \pi_0 u_0$
and, for $n = 1, \dots, N_{\mathcal{I}}$ and all $v_{\mathcal{T}_n} \in X_n$

$$\int_{\Omega} \frac{u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}}{\tau_n} v_{\mathcal{T}_n} + \mathbf{a}(\theta \nabla u_{\mathcal{T}_n}^n + (1 - \theta) \nabla u_{\mathcal{T}_{n-1}}^{n-1}, v_{\mathcal{T}_n})$$

$$= \int_{\Omega} f v_{\mathcal{T}_n}$$

with

$$\mathbf{a}(u, v) = d(\nabla u, \nabla v) + (\mathbf{a} \cdot \nabla u, v) + r(u, v),$$

Discrete Problem

Find $u_{\mathcal{T}_n}^n \in X_n$, $0 \leq n \leq N_{\mathcal{I}}$, such that $u_{\mathcal{T}_0}^0 = \pi_0 u_0$
and, for $n = 1, \dots, N_{\mathcal{I}}$ and all $v_{\mathcal{T}_n} \in X_n$

$$\begin{aligned} & \int_{\Omega} \frac{u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}}{\tau_n} v_{\mathcal{T}_n} + \mathbf{a}(\theta \nabla u_{\mathcal{T}_n}^n + (1 - \theta) \nabla u_{\mathcal{T}_{n-1}}^{n-1}, v_{\mathcal{T}_n}) \\ & + \sum_{K \in \tilde{\mathcal{T}}_n} \delta_K \int_K \left(\frac{u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}}{\tau_n} + L(\theta u_{\mathcal{T}_n}^n + (1 - \theta) u_{\mathcal{T}_{n-1}}^{n-1}) \right) \mathbf{a} \cdot \nabla v_{\mathcal{T}_n} \\ & = \int_{\Omega} f v_{\mathcal{T}_n} + \sum_{K \in \tilde{\mathcal{T}}_n} \delta_K \int_K f \mathbf{a} \cdot \nabla v_{\mathcal{T}_n} \end{aligned}$$

with

$$\mathbf{a}(u, v) = d(\nabla u, \nabla v) + (\mathbf{a} \cdot \nabla u, v) + r(u, v),$$

$$Lv = -\operatorname{div}(d \nabla u) + \mathbf{a} \cdot \nabla u + ru$$



Basic Steps



Basic Steps

- ▶ Error and residual are equivalent.



Basic Steps

- ▶ Error and residual are equivalent.
- ▶ The residual splits into a spatial and a temporal residual.



Basic Steps

- ▶ Error and residual are equivalent.
- ▶ The residual splits into a spatial and a temporal residual.
- ▶ The norm of the sum of these is equivalent to the sum of their norms.



Basic Steps

- ▶ Error and residual are equivalent.
- ▶ The residual splits into a spatial and a temporal residual.
- ▶ The norm of the sum of these is equivalent to the sum of their norms.
- ▶ Derive a reliable, efficient and robust error indicator for the spatial residual.



Basic Steps

- ▶ Error and residual are equivalent.
- ▶ The residual splits into a spatial and a temporal residual.
- ▶ The norm of the sum of these is equivalent to the sum of their norms.
- ▶ Derive a reliable, efficient and robust error indicator for the spatial residual.
- ▶ Derive a reliable, efficient and robust error indicator for the temporal residual.



Equivalence of Error and Residual



Equivalence of Error and Residual

- ▶ $u_{\mathcal{I}}$ continuous piece-wise affine, equals $u_{\mathcal{T}_n}^n$ at t_n .



Equivalence of Error and Residual

- ▶ $u_{\mathcal{I}}$ continuous piece-wise affine, equals $u_{\mathcal{T}_n}^n$ at t_n .
- ▶ Residual:

$$\begin{aligned}\langle R(u_{\mathcal{I}}), v \rangle &= (f, v) - (\partial_t u_{\mathcal{I}}, v) - (d \nabla u_{\mathcal{I}}, \nabla v) \\ &\quad - (\mathbf{a} \cdot \nabla u_{\mathcal{I}}, v) - (r u_{\mathcal{I}}, v)\end{aligned}$$



Equivalence of Error and Residual

- ▶ $u_{\mathcal{I}}$ continuous piece-wise affine, equals $u_{\mathcal{T}_n}^n$ at t_n .
- ▶ Residual:

$$\begin{aligned}\langle R(u_{\mathcal{I}}), v \rangle &= (f, v) - (\partial_t u_{\mathcal{I}}, v) - (d \nabla u_{\mathcal{I}}, \nabla v) \\ &\quad - (\mathbf{a} \cdot \nabla u_{\mathcal{I}}, v) - (r u_{\mathcal{I}}, v)\end{aligned}$$

- ▶ Lower bound:

$$\|R(u_{\mathcal{I}})\|_{L^2(t_{n-1}, t_n; H^{-1}(\Omega))} \leq \sqrt{2} \|u - u_{\mathcal{I}}\|_{X(t_{n-1}, t_n)}$$



Equivalence of Error and Residual

- ▶ $u_{\mathcal{I}}$ continuous piece-wise affine, equals $u_{\mathcal{T}_n}^n$ at t_n .
- ▶ Residual:

$$\begin{aligned}\langle R(u_{\mathcal{I}}), v \rangle &= (f, v) - (\partial_t u_{\mathcal{I}}, v) - (d \nabla u_{\mathcal{I}}, \nabla v) \\ &\quad - (\mathbf{a} \cdot \nabla u_{\mathcal{I}}, v) - (r u_{\mathcal{I}}, v)\end{aligned}$$

- ▶ Lower bound:

$$\|R(u_{\mathcal{I}})\|_{L^2(t_{n-1}, t_n; H^{-1}(\Omega))} \leq \sqrt{2} \|u - u_{\mathcal{I}}\|_{X(t_{n-1}, t_n)}$$

- ▶ Upper bound:

$$\|u - u_{\mathcal{I}}\|_{X(0, t_n)} \leq \left\{ 4 \|u_0 - \pi_0 u_0\|^2 + 6 \|R(u_{\mathcal{I}})\|_{L^2(0, t_n; H^{-1}(\Omega))}^2 \right\}^{\frac{1}{2}}$$



Proof of the Equivalence



Proof of the Equivalence

- ▶ Relation of residual and error:

$$\langle R(u_{\mathcal{I}}), v \rangle = (\partial_t e, v) - (\mathbf{a} \cdot \nabla e, v) - (d \nabla e, \nabla v) - (r e, v)$$



Proof of the Equivalence

- ▶ Relation of residual and error:

$$\langle R(u_{\mathcal{I}}), v \rangle = (\partial_t e, v) - (\mathbf{a} \cdot \nabla e, v) - (d \nabla e, \nabla v) - (r e, v)$$

- ▶ Lower bound: Definition of primal and dual norm plus Cauchy-Schwarz inequality.



Proof of the Equivalence

- ▶ Relation of residual and error:

$$\langle R(u_{\mathcal{I}}), v \rangle = (\partial_t e, v) - (\mathbf{a} \cdot \nabla e, v) - (d \nabla e, \nabla v) - (re, v)$$

- ▶ Lower bound: Definition of primal and dual norm plus Cauchy-Schwarz inequality.
- ▶ Upper bound: Parabolic energy estimate with $v = e$ as test-function.



Decomposition of the Residual



Decomposition of the Residual

- ▶ Temporal residual:

$$\begin{aligned}\langle R_{\tau}(u_{\mathcal{I}}), v \rangle &= (d \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{I}}), \nabla v) + (\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{I}}), v) \\ &\quad + (r(u_{\mathcal{T}_n}^n - u_{\mathcal{I}}), v)\end{aligned}$$



Decomposition of the Residual

- ▶ Temporal residual:

$$\begin{aligned}\langle R_\tau(u_{\mathcal{I}}), v \rangle &= (d\nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{I}}), \nabla v) + (\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{I}}), v) \\ &\quad + (r(u_{\mathcal{T}_n}^n - u_{\mathcal{I}}), v)\end{aligned}$$

- ▶ Spatial residual:

$$\begin{aligned}\langle R_h(u_{\mathcal{I}}), v \rangle &= (f, v) - (\partial_t u_{\mathcal{I}}, v) - (d\nabla u_{\mathcal{T}_n}^n, \nabla v) \\ &\quad - (\mathbf{a} \cdot \nabla u_{\mathcal{T}_n}^n, v) - (r u_{\mathcal{T}_n}^n, v)\end{aligned}$$



Decomposition of the Residual

- ▶ Temporal residual:

$$\begin{aligned}\langle R_\tau(u_{\mathcal{I}}), v \rangle &= (d\nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{I}}), \nabla v) + (\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{I}}), v) \\ &\quad + (r(u_{\mathcal{T}_n}^n - u_{\mathcal{I}}), v)\end{aligned}$$

- ▶ Spatial residual:

$$\begin{aligned}\langle R_h(u_{\mathcal{I}}), v \rangle &= (f, v) - (\partial_t u_{\mathcal{I}}, v) - (d\nabla u_{\mathcal{T}_n}^n, \nabla v) \\ &\quad - (\mathbf{a} \cdot \nabla u_{\mathcal{T}_n}^n, v) - (r u_{\mathcal{T}_n}^n, v)\end{aligned}$$

- ▶ Splitting: $R(u_{\mathcal{I}}) = R_\tau(u_{\mathcal{I}}) + R_h(u_{\mathcal{I}})$



Decomposition of the Residual

- ▶ Temporal residual:

$$\begin{aligned}\langle R_\tau(u_{\mathcal{I}}), v \rangle &= (d\nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{I}}), \nabla v) + (\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{I}}), v) \\ &\quad + (r(u_{\mathcal{T}_n}^n - u_{\mathcal{I}}), v)\end{aligned}$$

- ▶ Spatial residual:

$$\begin{aligned}\langle R_h(u_{\mathcal{I}}), v \rangle &= (f, v) - (\partial_t u_{\mathcal{I}}, v) - (d\nabla u_{\mathcal{T}_n}^n, \nabla v) \\ &\quad - (\mathbf{a} \cdot \nabla u_{\mathcal{T}_n}^n, v) - (r u_{\mathcal{T}_n}^n, v)\end{aligned}$$

- ▶ Splitting: $R(u_{\mathcal{I}}) = R_\tau(u_{\mathcal{I}}) + R_h(u_{\mathcal{I}})$
- ▶ Estimate for $L^2(t_{n-1}, t_n; H^{-1}(\Omega))$ -norms:

$$\begin{aligned}\frac{1}{5} \{ \|R_\tau(u_{\mathcal{I}})\|^2 + \|R_h(u_{\mathcal{I}})\|^2 \}^{\frac{1}{2}} &\leq \|R_\tau(u_{\mathcal{I}}) + R_h(u_{\mathcal{I}})\| \\ &\leq \|R_\tau(u_{\mathcal{I}})\| + \|R_h(u_{\mathcal{I}})\|\end{aligned}$$



Motivation of the Lower Bound



Motivation of the Lower Bound

- ▶ Strengthened Cauchy-Schwarz inequality for $v = c$ and $w = \frac{b-t}{b-a}$:

$$\int_a^b vw = \frac{1}{2}c(b-a) = \frac{\sqrt{3}}{2} \|v\|_{(a,b)} \|w\|_{(a,b)}$$



Motivation of the Lower Bound

- ▶ Strengthened Cauchy-Schwarz inequality for $v = c$ and $w = \frac{b-t}{b-a}$:

$$\int_a^b vw = \frac{1}{2}c(b-a) = \frac{\sqrt{3}}{2}\|v\|_{(a,b)}\|w\|_{(a,b)}$$

- ▶ Hence:

$$\|v + w\|_{(a,b)}^2 \geq \left(1 - \frac{\sqrt{3}}{2}\right) \left\{ \|v\|_{(a,b)}^2 + \|w\|_{(a,b)}^2 \right\}$$



Proof of the Lower Bound



Proof of the Lower Bound

- ▶ $R_h(u_{\mathcal{I}})$ is piece-wise constant.



Proof of the Lower Bound

- ▶ $R_h(u_{\mathcal{I}})$ is piece-wise constant.
- ▶ $R_{\tau}(u_{\mathcal{I}})$ is piece-wise affine: $R_{\tau}(u_{\mathcal{I}}) = \frac{t_n - t}{\tau_n} \rho^n$ with

$$\begin{aligned} \langle \rho^n, v \rangle &= (d \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), \nabla v) + (\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v) \\ &\quad + (r(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v). \end{aligned}$$



Proof of the Lower Bound

- ▶ $R_h(u_{\mathcal{I}})$ is piece-wise constant.
- ▶ $R_\tau(u_{\mathcal{I}})$ is piece-wise affine: $R_\tau(u_{\mathcal{I}}) = \frac{t_n - t}{\tau_n} \rho^n$ with

$$\begin{aligned} \langle \rho^n, v \rangle &= (d \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), \nabla v) + (\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v) \\ &\quad + (r(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v). \end{aligned}$$

- ▶ Choose $v, w \in H_0^1(\Omega)$ such that

$$\begin{aligned} \|v\| &= \|R_h(u_{\mathcal{I}})\|_*, & \langle R_h(u_{\mathcal{I}}), v \rangle &= \|R_h(u_{\mathcal{I}})\|_*^2, \\ \|w\| &= \|\rho^n\|_*, & \langle \rho^n, w \rangle &= \|\rho^n\|_*^2. \end{aligned}$$



Proof of the Lower Bound

- ▶ $R_h(u_{\mathcal{I}})$ is piece-wise constant.
- ▶ $R_{\tau}(u_{\mathcal{I}})$ is piece-wise affine: $R_{\tau}(u_{\mathcal{I}}) = \frac{t_n-t}{\tau_n} \rho^n$ with

$$\begin{aligned} \langle \rho^n, v \rangle &= (d \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), \nabla v) + (\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v) \\ &\quad + (r(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v). \end{aligned}$$

- ▶ Choose $v, w \in H_0^1(\Omega)$ such that

$$\begin{aligned} \|v\| &= \|R_h(u_{\mathcal{I}})\|_*, & \langle R_h(u_{\mathcal{I}}), v \rangle &= \|R_h(u_{\mathcal{I}})\|_*^2, \\ \|w\| &= \|\rho^n\|_*, & \langle \rho^n, w \rangle &= \|\rho^n\|_*^2. \end{aligned}$$

- ▶ Insert $3\left(\frac{t-t_{n-1}}{\tau_n}\right)^2 v + \frac{t_n-t}{\tau_n} w$ as test-function in representation of $R(u_{\mathcal{I}})$.



Estimation of the Spatial Residual



Estimation of the Spatial Residual

- ▶ Spatial error indicator $\eta_{\mathcal{T}_n}^n$:

$$\eta_{\mathcal{T}_n}^n = \left\{ \sum_{K \in \tilde{\mathcal{T}}_n} \alpha_K^2 \|R_K\|_K^2 + \sum_{E \in \mathcal{E}_{\tilde{\mathcal{T}}_n}} \varepsilon^{-\frac{1}{2}} \alpha_E \|R_E\|_E^2 \right\}^{\frac{1}{2}}.$$



Estimation of the Spatial Residual

- ▶ Spatial error indicator $\eta_{\mathcal{T}_n}^n$:

$$\eta_{\mathcal{T}_n}^n = \left\{ \sum_{K \in \tilde{\mathcal{T}}_n} \alpha_K^2 \|R_K\|_K^2 + \sum_{E \in \mathcal{E}_{\tilde{\mathcal{T}}_n}} \varepsilon^{-\frac{1}{2}} \alpha_E \|R_E\|_E^2 \right\}^{\frac{1}{2}}.$$

- ▶ R_K and R_E are the usual element and interface residuals.



Estimation of the Spatial Residual

- ▶ Spatial error indicator $\eta_{\mathcal{T}_n}^n$:

$$\eta_{\mathcal{T}_n}^n = \left\{ \sum_{K \in \tilde{\mathcal{T}}_n} \alpha_K^2 \|R_K\|_K^2 + \sum_{E \in \mathcal{E}_{\tilde{\mathcal{T}}_n}} \varepsilon^{-\frac{1}{2}} \alpha_E \|R_E\|_E^2 \right\}^{\frac{1}{2}}.$$

- ▶ R_K and R_E are the usual element and interface residuals.
- ▶ Standard arguments for stationary problems yield:

$$\begin{aligned} \| \|R_h(u_{\mathcal{I}}) \| \|_* &\leq c^\dagger \eta_{\mathcal{T}_n}^n, \\ \eta_{\mathcal{T}_n}^n &\leq c_\dagger \| \|R_h(u_{\mathcal{I}}) \| \|_* . \end{aligned}$$

Estimation of the Spatial Residual

- ▶ Spatial error indicator $\eta_{\mathcal{T}_n}^n$:

$$\eta_{\mathcal{T}_n}^n = \left\{ \sum_{K \in \tilde{\mathcal{T}}_n} \alpha_K^2 \|R_K\|_K^2 + \sum_{E \in \mathcal{E}_{\tilde{\mathcal{T}}_n}} \varepsilon^{-\frac{1}{2}} \alpha_E \|R_E\|_E^2 \right\}^{\frac{1}{2}}.$$

- ▶ R_K and R_E are the usual element and interface residuals.
- ▶ Standard arguments for stationary problems yield:

$$\begin{aligned} \| \|R_h(u_{\mathcal{I}})\| \|_* &\leq c^\dagger \eta_{\mathcal{T}_n}^n, \\ \eta_{\mathcal{T}_n}^n &\leq c_\dagger \| \|R_h(u_{\mathcal{I}})\| \|_* . \end{aligned}$$

- ▶ $c^\dagger c_\dagger$ only depend on the polynomial degrees and on the shape parameters of the partitions $\tilde{\mathcal{T}}_n$.



Estimation of the Temporal Residual



Estimation of the Temporal Residual

- Recall $R_\tau(u_{\mathcal{I}}) = \frac{t_n - t}{\tau_n} \rho^n$ with

$$\begin{aligned} \langle \rho^n, v \rangle &= (d \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), \nabla v) + (\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v) \\ &\quad + (r(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v). \end{aligned}$$



Estimation of the Temporal Residual

- ▶ Recall $R_\tau(u_{\mathcal{I}}) = \frac{t_n - t}{\tau_n} \rho^n$ with

$$\begin{aligned} \langle \rho^n, v \rangle &= (d \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), \nabla v) + (\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v) \\ &\quad + (r(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v). \end{aligned}$$

- ▶ Upper bound:

$$\|\rho^n\|_* \leq \left\{ \|u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}\| + \|\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_* \right\}$$

Estimation of the Temporal Residual

- ▶ Recall $R_\tau(u_{\mathcal{I}}) = \frac{t_n - t}{\tau_n} \rho^n$ with

$$\begin{aligned} \langle \rho^n, v \rangle &= (d \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), \nabla v) + (\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v) \\ &\quad + (r(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v). \end{aligned}$$

- ▶ Upper bound:

$$\|\|\| \rho^n \|\|_* \leq \left\{ \|\| u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1} \|\| + \|\| \mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}) \|\|_* \right\}$$

- ▶ Follows from definition of ρ^n and $\|\|\cdot\|\|_*$.



Estimation of the Temporal Residual

- ▶ Recall $R_\tau(u_{\mathcal{I}}) = \frac{t_n - t}{\tau_n} \rho^n$ with

$$\begin{aligned} \langle \rho^n, v \rangle &= (d \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), \nabla v) + (\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v) \\ &\quad + (r(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v). \end{aligned}$$

- ▶ Upper bound:

$$\|\|\rho^n\|\|_* \leq \left\{ \|\|u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}\|\| + \|\|\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|\|_* \right\}$$

- ▶ Follows from definition of ρ^n and $\|\|\cdot\|\|_*$.
- ▶ Lower bound:

$$\frac{1}{3} \left\{ \|\|u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}\|\| + \|\|\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|\|_* \right\} \leq \|\|\rho^n\|\|_*$$



Proof of the Lower Bound



Proof of the Lower Bound

- ▶ Set $w^n = u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}$ and choose $v \in H_0^1(\Omega)$ with $\|v\| = \|\mathbf{a} \cdot \nabla w^n\|_*$ and $(\mathbf{a} \cdot \nabla w^n, v) = \|\mathbf{a} \cdot \nabla w^n\|_*^2$

Proof of the Lower Bound

- ▶ Set $w^n = u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}$ and choose $v \in H_0^1(\Omega)$ with $\|v\| = \|\mathbf{a} \cdot \nabla w^n\|_*$ and $(\mathbf{a} \cdot \nabla w^n, v) = \|\mathbf{a} \cdot \nabla w^n\|_*^2$
- ▶ Insert $\frac{1}{2}w^n + \frac{1}{2}v$ in the definition of ρ^n :

$$\begin{aligned}
 & \langle \rho^n, \frac{1}{2}w^n + \frac{1}{2}v \rangle \\
 &= \underbrace{\frac{1}{2}(d\nabla w^n, \nabla w^n) + \frac{1}{2}(rw^n, w^n)}_{=\frac{1}{2}\|w^n\|^2} + \underbrace{\frac{1}{2}(\mathbf{a} \cdot \nabla w^n, w^n)}_{=0} \\
 &+ \underbrace{\frac{1}{2}(d\nabla w^n, \nabla v) + \frac{1}{2}(rw^n, v)}_{\geq -\frac{1}{2}\|w^n\| \|\mathbf{a} \cdot \nabla w^n\|_*} + \underbrace{\frac{1}{2}(\mathbf{a} \cdot \nabla w^n, v)}_{=\frac{1}{2}\|\mathbf{a} \cdot \nabla w^n\|_*^2}
 \end{aligned}$$



Estimation of the Convective Derivative I



Estimation of the Convective Derivative I

- ▶ Assume that $\|\mathbf{a}\|_\infty \leq c_c d$.



Estimation of the Convective Derivative I

- ▶ Assume that $\|\mathbf{a}\|_\infty \leq c_c d$.
- ▶ Friedrichs' inequality implies

$$\begin{aligned}(\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v) &\leq \|\mathbf{a}\|_\infty \|\nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\| \|v\| \\ &\leq \|\mathbf{a}\|_\infty \|\nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\| c_\Omega \|\nabla v\|\end{aligned}$$



Estimation of the Convective Derivative I

- ▶ Assume that $\|\mathbf{a}\|_\infty \leq c_c d$.
- ▶ Friedrichs' inequality implies

$$\begin{aligned}(\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), v) &\leq \|\mathbf{a}\|_\infty \|\nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\| \|v\| \\ &\leq \|\mathbf{a}\|_\infty \|\nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\| c_\Omega \|\nabla v\|\end{aligned}$$

- ▶ Hence $\|\|\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|\|_* \leq c_c c_\Omega \|u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}\|$ and $\|\|\mathbf{a} \cdot \nabla(u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|\|_*$ is equivalent to $\|u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}\|$.



Estimation of the Convective Derivative II



Estimation of the Convective Derivative II

- ▶ Assume that $\|\mathbf{a}\|_\infty \gg d$.



Estimation of the Convective Derivative II

- ▶ Assume that $\|\mathbf{a}\|_\infty \gg d$.
- ▶ Consider the auxiliary problem

$$d(\nabla v_{\mathcal{T}_n}^n, \nabla \varphi) + r(v_{\mathcal{T}_n}^n, \varphi) = (\mathbf{a} \cdot \nabla (u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), \varphi) \quad (*)$$

with variational and discrete solutions Φ and $\Phi_{\mathcal{T}_n}$.

Estimation of the Convective Derivative II

- ▶ Assume that $\|\mathbf{a}\|_\infty \gg d$.
- ▶ Consider the auxiliary problem

$$d(\nabla v_{\mathcal{T}_n}^n, \nabla \varphi) + r(v_{\mathcal{T}_n}^n, \varphi) = (\mathbf{a} \cdot \nabla (u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), \varphi) \quad (*)$$

with variational and discrete solutions Φ and $\Phi_{\mathcal{T}_n}$.

- ▶ Then $\|\Phi\| = \|\mathbf{a} \cdot \nabla (u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_*$,
 $\|\Phi_{\mathcal{T}_n}\| \leq \|\mathbf{a} \cdot \nabla (u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_*$ and therefore

$$\begin{aligned} \frac{1}{3} \{ \|\Phi_{\mathcal{T}_n}\| + \|\Phi - \Phi_{\mathcal{T}_n}\| \} &\leq \|\mathbf{a} \cdot \nabla (u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_* \\ &\leq \|\Phi_{\mathcal{T}_n}\| + \|\Phi - \Phi_{\mathcal{T}_n}\|. \end{aligned}$$



Estimation of the Convective Derivative II

- ▶ Assume that $\|\mathbf{a}\|_\infty \gg d$.
- ▶ Consider the auxiliary problem

$$d(\nabla v_{\mathcal{T}_n}^n, \nabla \varphi) + r(v_{\mathcal{T}_n}^n, \varphi) = (\mathbf{a} \cdot \nabla (u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), \varphi) \quad (*)$$

with variational and discrete solutions Φ and $\Phi_{\mathcal{T}_n}$.

- ▶ Then $\|\Phi\| = \|\mathbf{a} \cdot \nabla (u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_*$,
 $\|\Phi_{\mathcal{T}_n}\| \leq \|\mathbf{a} \cdot \nabla (u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_*$ and therefore

$$\begin{aligned} \frac{1}{3} \{ \|\Phi_{\mathcal{T}_n}\| + \|\Phi - \Phi_{\mathcal{T}_n}\| \} &\leq \|\mathbf{a} \cdot \nabla (u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_* \\ &\leq \|\Phi_{\mathcal{T}_n}\| + \|\Phi - \Phi_{\mathcal{T}_n}\|. \end{aligned}$$

- ▶ Transition condition implies that $\|\Phi - \Phi_{\mathcal{T}_n}\|$ is equivalent to every robust, e.g. residual, error indicator $\eta_{\mathcal{T}}^n$ for (*).



Estimation of the Convective Derivative II

- ▶ Assume that $\|\mathbf{a}\|_\infty \gg d$.
- ▶ Consider the auxiliary problem

$$d(\nabla v_{\mathcal{T}_n}^n, \nabla \varphi) + r(v_{\mathcal{T}_n}^n, \varphi) = (\mathbf{a} \cdot \nabla (u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1}), \varphi) \quad (*)$$

with variational and discrete solutions Φ and $\Phi_{\mathcal{T}_n}$.

- ▶ Then $\|\Phi\| = \|\mathbf{a} \cdot \nabla (u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_*$,
 $\|\Phi_{\mathcal{T}_n}\| \leq \|\mathbf{a} \cdot \nabla (u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_*$ and therefore

$$\begin{aligned} \frac{1}{3} \{ \|\Phi_{\mathcal{T}_n}\| + \|\Phi - \Phi_{\mathcal{T}_n}\| \} &\leq \|\mathbf{a} \cdot \nabla (u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_* \\ &\leq \|\Phi_{\mathcal{T}_n}\| + \|\Phi - \Phi_{\mathcal{T}_n}\|. \end{aligned}$$

- ▶ Transition condition implies that $\|\Phi - \Phi_{\mathcal{T}_n}\|$ is equivalent to every robust, e.g. residual, error indicator $\eta_{\mathcal{T}}^n$ for (*).
- ▶ Hence $\|\mathbf{a} \cdot \nabla (u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1})\|_*$ is equivalent to $\|\Phi_{\mathcal{T}_n}\| + \eta_{\mathcal{T}}^n$.



A Posteriori Error Estimate

A Posteriori Error Estimate

- Define the space-time error estimator by:

$$\eta^n = \tau_n^{\frac{1}{2}} \left[\underbrace{\left(\eta_{\mathcal{T}_n}^n \right)^2}_{\text{spatial}} + \underbrace{\| \| u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1} \| \|^2}_{\text{temporal}} + \left(\eta_{\tau}^n \right)^2 \right]^{\frac{1}{2}}.$$

A Posteriori Error Estimate

- Define the space-time error estimator by:

$$\eta^n = \tau_n^{\frac{1}{2}} \left[\underbrace{\left(\eta_{\mathcal{T}_n}^n \right)^2}_{\text{spatial}} + \underbrace{\| \| u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1} \| \|^2}_{\text{temporal}} + \left(\eta_{\tau}^n \right)^2 \right]^{\frac{1}{2}}.$$

- Then

$$\| e \|_{X(0,T)} \leq c^* \left\{ \| u_0 - \pi_0 u_0 \| \|^2 + \sum_{n=1}^{N_{\mathcal{I}}} \left(\eta^n \right)^2 \right\}^{\frac{1}{2}},$$

$$\eta^n \leq c_* \| e \|_{X(t_{n-1}, t_n)}.$$

A Posteriori Error Estimate

- Define the space-time error estimator by:

$$\eta^n = \tau_n^{\frac{1}{2}} \left[\underbrace{\left(\eta_{\mathcal{T}_n}^n \right)^2}_{\text{spatial}} + \underbrace{\| \| u_{\mathcal{T}_n}^n - u_{\mathcal{T}_{n-1}}^{n-1} \| \|^2}_{\text{temporal}} + \left(\eta_{\tau}^n \right)^2 \right]^{\frac{1}{2}}.$$

- Then

$$\| e \|_{X(0,T)} \leq c^* \left\{ \| u_0 - \pi_0 u_0 \| \|^2 + \sum_{n=1}^{N_{\mathcal{I}}} \left(\eta^n \right)^2 \right\}^{\frac{1}{2}},$$

$$\eta^n \leq c_* \| e \|_{X(t_{n-1}, t_n)}.$$

- $c_* c^*$ only depends on the polynomial degrees and the shape parameters of the partitions $\tilde{\mathcal{T}}_n$.





References



A posteriori error estimates for finite element discretizations of the heat equation, *Calcolo* **40** (2003), no. 3, 195 – 212.






References

-  A posteriori error estimates for finite element discretizations of the heat equation, *Calcolo* **40** (2003), no. 3, 195 – 212.
-  Robust a posteriori error estimates for nonstationary convection-diffusion equations, *SIAM J. Numer. Anal.* **43** (2005), no. 4, 1783–1802







References

-  A posteriori error estimates for finite element discretizations of the heat equation, *Calcolo* **40** (2003), no. 3, 195 – 212.
-  Robust a posteriori error estimates for nonstationary convection-diffusion equations, *SIAM J. Numer. Anal.* **43** (2005), no. 4, 1783–1802
-  Robust a posteriori error estimates for stationary convection-diffusion equations, *SIAM J. Numer. Anal.* **43** (2005), no. 4, 1766–1782



References

-  A posteriori error estimates for finite element discretizations of the heat equation, *Calcolo* **40** (2003), no. 3, 195 – 212.
-  Robust a posteriori error estimates for nonstationary convection-diffusion equations, *SIAM J. Numer. Anal.* **43** (2005), no. 4, 1783–1802
-  Robust a posteriori error estimates for stationary convection-diffusion equations, *SIAM J. Numer. Anal.* **43** (2005), no. 4, 1766–1782
-  A posteriori error analysis of space-time finite element discretizations of the time-dependent Stokes equations, *Calcolo* (2010) (electronically)